

Change in myocardial oxygen consumption employing continuous-flow LVAD with cardiac beat synchronizing system, in acute ischemic heart failure models

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Abstract Aiming the ‘Bridge to Recovery’ course, we have developed a novel left ventricular assist device (LVAD) controlling system. It can change the rotational speed of the continuous flow LVAD, EVAHEART, synchronized with the cardiac beat. Employing this system, we have already demonstrated that myocardial oxygen consumption (MVO₂), which is considered to be equivalent to native heart load, changes in the hearts of normal goats. Herein, we examined changes in goats with acute ischemic heart failure. We studied 14 goats (56.1 ± 6.9 kg) with acute ischemic heart failure due to coronary microsphere embolization. We installed the EVAHEART and drive in four modes: “circuit-clamp”, “continuous support”, “counter-pulse”, and “co-pulse”, with 50 and 100 % bypass. In comparison to the circuit-clamp mode, MVO₂ was reduced to 70.4 ± 17.9 % in the counter-pulse mode

and increased to 90.3 ± 14.5 % in the co-pulse mode, whereas it was 80.0 ± 14.5 % in the continuous mode, with 100 % bypass ($p < 0.05$). The same difference was confirmed with 50 % bypass. This means that we may have a chance to change the native heart load by controlling the LVAD rotation in synchrony with the cardiac rhythm, so we named our controller as the Native Heart Load Control System (NHLCS). Employing changeable MVO₂ with NHLCS according to the patient’s condition may provide more opportunity for native heart recovery with LVAD, especially for patients with ischemic heart diseases.

Keywords Continuous-flow LVAD · NHLCS · Myocardial oxygen consumption · Synchronized with cardiac beat

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Introduction

Patients with severe heart failure are treated with a multi-disciplinary approach involving conservative medical management, and prognoses have improved remarkably in recent years. And some patients who are resistant to current medical treatments are considered to have indications for left ventricular assist device (LVAD) implantation or heart transplantation. But, given the scarcity of donor hearts available in Japan, the number of patients with LVAD for severe chronic heart failure is rapidly increasing. Thus, there is an urgent need to establish methods which can improve the courses of patients with LVAD, especially aiming for the ‘Bridge to Recovery’ course (BTR) with the recovery of the native heart function [1–5].

Obviously, now is the time for continuous-flow LVAD. Due to its small size, this LVAD can be installed inside the body. Patients can be discharged from the hospital, and the

risk of infection would thus presumably be reduced. The favorable clinical outcomes add impetus to this trend [6]. On the other hand, many reports comparing the systemic effects of pulsatile and continuous-flow LVAD have not described favorable results [6–27]. We consider the merit of our novel system to be its potential ability to provide physiological circulation.

Given this situation, we developed and introduced a power-control unit for centrifugal LVAD, the EVAHEART (Sun Medical, Nagano, Tokyo, Japan) [28, 29]. With this unit, we drive the EVAHEART in synchrony with the native rhythm of the heart, by adjusting the time span and the rotational speed (RS) in the systolic and diastolic phases [30–36]. Ours is the first trial to evaluate continuous-flow LVAD with the pulsatile driving technique. Apparently, the LVAD can decrease the native heart load by aiding native heart function, and decreasing left ventricular end-diastolic pressure and volume. The most suitable parameter for evaluating the native heart load is myocardial oxygen consumption (MVO₂), because it reflects precisely the left ventricular pressure volume area (PVA), which is considered to be energetically equivalent to the sum of external energy and potential energy [37–41]. There are many reports showing the effect of reducing the native heart load employing LVAD [42–46]. In these reports, MVO₂ was reduced by LVAD, regardless of whether it was continuous [42–44] or pulsatile [45, 46]. In addition, this trend does not depend on the condition of the native heart. This effect has been confirmed in both normal [42, 44, 46] and failing [43, 45] hearts.

Thus, we have recently focused on MVO₂ in order to evaluate our novel system, and found that MVO₂ can be altered according to the control mode in goats with normal hearts [31]. If we can achieve an appropriate amount of MVO₂ by controlling the rotation of continuous-flow LVAD, in synchrony with the cardiac beat, we may have the opportunity to enhance the function of the native heart supported by LVAD. However, before application in a clinical situation, it is necessary to test this design in models of heart failure, which might be completely different from normal heart models. Therefore, in the present study, we examined changes in MVO₂ in goats with acute ischemic heart failure. Herein, our aim is to show that MVO₂ can be changed employing our novel control method in an acute ischemic heart failure model.

Materials and methods

Animals

We studied 14 goats with acute ischemic heart failure (56.1 ± 6.9 kg) due to coronary microsphere embolization.

The animals used in this study were maintained in accordance with the guidelines of the Committee on Animal Studies at the National Cerebral and Cardiovascular Center. This study was approved by the National Cerebral and Cardiovascular Center Animal Investigation Committee. Institutional guidelines for the care and use of laboratory animals have been observed.

Surgical procedures, implanted devices

The animals were tranquilized with ketamine hydrochloride (8–10 mg/kg intramuscularly) and then intubated and mechanically ventilated. The goats were anesthetized with isoflurane (1–3 vol/100 ml in oxygen), and then draped and prepped in the right lateral recumbent position. A left thoracotomy was performed and the fifth costal bone was resected. We retained the left intra-thoracic artery and vein to measure the aortic pressure (AoP) and the central vein pressure (CVP), and also to collect data for blood gas analysis. The blood flows in the ascending aorta, LVAD, and coronary artery (left main trunk, LMT) were measured using a flow meter. We used an electromagnetic flow meter (16–22 mm in diameter, EMF-1000, Nihon Kohden, Tokyo, Japan) for the aorta, an ultrasonic flow meter (3–4 mm, HQD3FSB, Transonic Systems, Ithaca, NY, USA) for the LMT, and another ultrasonic flow meter (16 mm, TS420, Transonic Systems) for the LVAD. After heparinization (200 U/kg), centrifugal LVAD, EVAHEART was installed. Inflow cannula was inserted from the left ventricular apex and the outflow conduit was to the descending aorta. A 6Fr conductance catheter (2S-RH-6DA-116, Taisho Biomed Instrument, Osaka, Japan) and a 4Fr micro-tip catheter pressure transducer (Millar Instruments, Houston, TX, USA) were inserted into the left ventricle from the anterior wall to collect data for the pressure volume curve of the left ventricle. Because the coronary sinus is connected to the accessory hemiazygos vein in goats, we inserted a Sarns retrograde cannula (10Fr, Terumo corp., Tokyo, Japan) into the coronary sinus from the accessory hemiazygos vein and thereby sampled coronary sinus vein blood. We calculated the MVO₂ by multiplying the difference in oxygen saturation between the artery (ScaO₂) and coronary sinus blood (ScvO₂), the hemoglobin concentration of arterial blood (aHb), and the amount of coronary flow (CoF) ($MVO_2 = (ScaO_2 - ScvO_2) \times 1.34 \times aHb \times CoF$). The aforementioned vital data were recorded in Labchart5 (ADInstruments, Bella Vista NSW, Australia).

Making left ventricular dysfunction models

To create the acute ischemic heart failure model, we micro-embolized the left anterior descending coronary artery

(LAD), as described in earlier reports [47–50]. A multi-purpose Judkins catheter (4Fr, Create Medic Co., LTD, Japan) was introduced through a long sheath (4Fr × 17 cm) into the left carotid artery toward the LAD under fluoroscopic guidance. We then injected approximately 0.3 million (0.005 million/kg) microspheres (50 μm in diameter) into the LAD. Ten minutes after this injection, we observed the animal’s general condition, including aortic flow. If aortic flow exceeded 60 % of the baseline value, we arbitrarily added half the amount of microspheres (0.0025 million/kg), to achieve a total amount of 0.30 ± 0.14 million. After 30 min of further observation, we collected data to assure stable optimal cardiac function. We planned to reduce and then maintain cardiac output at approximately 60 % of the native heart function documented prior to creation of the acute ischemic heart failure model.

Study protocol, LVAD control method

We controlled the AoP and CVP to ensure stable conditions during the examination. This assured that there were no changes in the afterload or the preload of the heart. Heart rate was also controlled. We controlled these values by adjusting the volume of infusion and changing the depth of anesthesia, not by using either vasodilators or catecholamines. We used 2 % lidocaine (1 mg/kg/h) and Nifekalant hydrochloride (0.4 mg/kg/h) during the experiment to prevent ventricular arrhythmias.

We previously reported the details of our novel pump controller, which can change the RS of the EVAHEART in synchrony with the cardiac cycle [30–36]. We defined the systolic phase as 35 % of the RR interval and the diastolic phase as 65 % of the RR interval, and we input the duration of each phase according to the heart rate. Our controller can change the RS of each phase, detecting the R wave from an electrocardiogram (ECG). The bypass rate (BR) was calculated by dividing the pump flow rate (PF) by the sum of the PF and aortic flow (AoF) rates.

Using this controller, we compared four driving modes in this study. The first was the “circuit-clamp” (pump-off) mode, clamping the LVAD circuit so as to evaluate the conditions of the native heart. The next was the “continuous support” mode, driving the LVAD continuously at a stable RS. This is the mode we usually apply in clinical situations. The third was the “counter-pulse” mode, in which we set the RS of the systolic phase to approximately 700 rpm, the minimum speed of the LVAD system, and adjusted the RS of the diastolic phase to achieve the most appropriate BR, as needed. In this study, the BRs were set at 50 and 100 %. The latter was the “co-pulse” mode. This mode was defined in an opposite manner; we set the RS of the diastolic phase to approximately 1,000 rpm so as to avoid inducing a reverse flow inside the LVAD circuit, and adjusted the RS of the systolic phase to achieve BRs of 50 and 100 % (Fig. 1). We obtained the various data at 5 min after setting each mode. This was considered to be a sufficient period for the animal’s condition to stabilize. In this study, we mainly evaluated the MVO2. The comparison was performed by repeated analysis of variance followed by Tukey’s multiple comparison test, and a *p* value less than 0.05 was considered as statistically significant.

Results

Sample waveforms of the ECG, AoP, CVP, left ventricular pressure (LVP), PF, AoF, CoF, RS, and the BR are shown in Fig. 2. In the continuous mode, the output of the native heart (AoF) was decreased by removing blood with the LVAD. The pulse pressure was also reduced as compared to that of the circuit-clamp mode. In the counter-pulse mode, increased RS in the diastolic phase produced much gentler AoP waveforms than those obtained with the continuous or the circuit-clamp mode. The gentle waveform resulted from a counter-pulse effect, much like that seen with intra-aortic balloon pumping, as we expected.

Fig. 1 Driving modes of NHLCS. We compared MVO2 in 4 modes: “circuit-clamp”, “continuous support”, “counter-pulse” (to raise RS in diastole), and “co-pulse” (to raise RS in systole), with 50 and 100 % bypass. We defined the systolic phase as 35 % of the RR interval and the diastolic phase as 65 % of the RR interval, and set the upper rotational speed so as to achieve an appropriate bypass rate, as needed

A) Circuit-Clamp (ie. No pump support)
 B) Continuous Mode (constant rotation)
 C) Counterpulse Mode (increase rotation in diastole)
 D) Copulse Mode (increase rotation in systole)

Spans of the systolic and the diastolic phase
 Systolic phase = 35% of RR interval, Diastolic phase = 65% of RR interval

How to define the rotational speed (RS, rpm) of C) and D)
 Low RS : Around 700-1000rpm, to avoid reverse flow inside the cf-LVAD circuit
 High RS : Adjust rotational speed to assure proper bypass rate to make

Bypass Rate (BR) (%) = Pump Flow/(Pump Flow + Ascending Aortic Flow)
 In this report, we controlled the BR to achieve 50(45-60)% and 100(90-110)%.

Although the PF waveform became almost flat, there was no change in the total amount of PF among the three driving modes (except the circuit-clamp mode). The amount of CoF in the diastolic phase was higher than with the other modes due to the counter-pulse effect. By contrast, in the co-pulse mode, the waveforms of AoP and PF were more precipitous than with the other mode, due to the higher RS in the systolic phase. The amount of CoF in the diastolic phase was lower than with the other three modes.

Hemodynamic parameters are presented in Table 1. Heart rate (HR), CVP, AoP, LVP, total flow (the sum of AoF and PF), and the BR are shown. The baseline data (before heart failure) are on the left, and those of acute ischemic heart failure models with each of the driving modes and BRs are on the right. In the right table, the total flow amount in the circuit-clamp mode is equivalent to native heart output with acute heart failure. The parameters shown are essentially 60 % of the baseline data. This means the amount of native heart output was reduced to approximately 60 %, as we expected. Considering the differences among driving modes with LVAD (other than the circuit-clamp mode), there were no significant differences in these hemodynamic parameters.

Figure 3 shows the MVO2 in each mode as a percentage of that in the circuit-clamp mode (=100 %). The MVO2 was decreased in continuous mode as compared to the circuit-clamp mode, regardless of the BR. This means that the LVAD would reduce the load on the native heart in the setting of acute heart failure. Comparing the MVO2 among each of the driving modes, it was lower in the counter-pulse mode and higher in the co-pulse mode than in the

continuous mode ($p < 0.05$) at both the 50 and the 100 % BR. With the 50 % BR, the MVO2 was 83.9 ± 14.8 % in the counter-pulse mode and 100.8 ± 9.0 % in the co-pulse mode, whereas it was 92.2 ± 9.0 % in the continuous support mode (Fig. 3a). The same trend was detected with the 100 % BR, where the MVO2 was 70.4 ± 17.9 % in the counter-pulse mode and 90.3 ± 14.5 % in the co-pulse mode, whereas it was 80.0 ± 14.5 % in the continuous support mode (Fig. 3b).

Figure 4 shows the end-diastolic volume of the left ventricle (EDV) in each mode as a percentage of that in the circuit-clamp mode (=100 %). The EDV was lower in the counter-pulse mode and higher in the co-pulse mode than in the continuous mode ($p < 0.05$) for both the 50 and the 100 % BR. With the 50 % BR, the EDV was 94.8 ± 3.5 % in the counter-pulse mode and 100.3 ± 3.3 % in the co-pulse mode, whereas it was 97.3 ± 3.1 % in the continuous support mode. The same trend was detected with the 100 % BR, where the EDV was 83.2 ± 8.2 % in the counter-pulse mode and 93.4 ± 8.0 % in the co-pulse mode, whereas it was 88.3 ± 8.6 % in the continuous support mode.

Figure 5 shows the echocardiographic images of the left ventricle in the end-diastolic phase. The upper chamber was the left ventricle, and the inflow cannula was inserted from the apex. The size of the left ventricle was significantly decreased in the counter-pulse mode (Fig. 5b) and increased in the co-pulse mode (Fig. 5c) as compared with that in the continuous mode (Fig. 5a).

Pressure volume curves for the left ventricle in the each of the modes with acute heart failure are shown in Fig. 6.

Fig. 2 Waveforms of pressure and flow. *PF* pump flow, *AoF* ascending aortic flow, *CoF* coronary flow, *RS* rotational speed, *BR* bypass rate. In the counter-pulse mode, increased RS resulted in gentler waveforms of AoP and PF in the diastolic phase. In the co-pulse mode, increased RS resulted in sharper waveforms of AoP and PF in the systolic phase

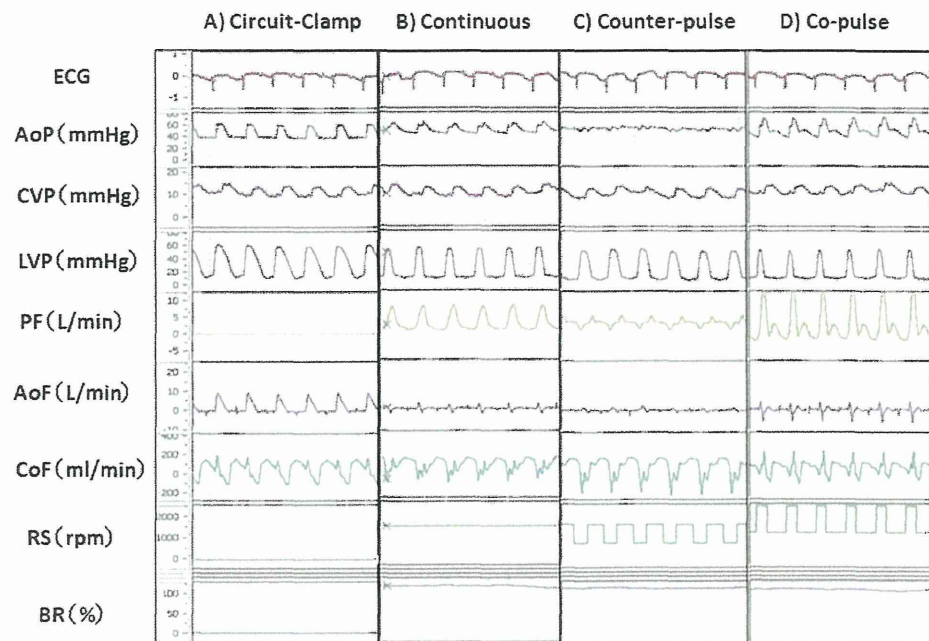


Table 1 Vital data at baseline and after embolization in each mode

Baseline Data		50% Bypass	Circuit-Clamp	Continuous	Counter-pulse	Co-pulse
HR	76.3 ± 11.7		80.6 ± 14.6	81.9 ± 15.6	79.2 ± 12.9	81.9 ± 12.4
Mean CVP (mmHg)	11.2 ± 5.6		14.6 ± 4.4	12.3 ± 4.0	13.2 ± 4.8	14.3 ± 3.7
Mean AoP	74.6 ± 14.7		66.7 ± 16.8	61.5 ± 10.3	62.3 ± 11.6	60.8 ± 10.9
Mean LVP	54.1 ± 14.9		46.3 ± 13.0	41.4 ± 8.8	40.8 ± 12.9	39.9 ± 12.4
Pump Flow(L/min)	0.0 ± 0.0		0.0 ± 0.0	1.6 ± 0.8	1.7 ± 0.7	1.6 ± 0.9
Total Flow (L/min)	4.8 ± 1.2		3.0 ± 1.1	3.4 ± 1.0	3.5 ± 0.9	3.4 ± 1.2
Bypass Rate (%)	0.0 ± 0.0		0.0 ± 0.0	53.4 ± 8.4	52.6 ± 9.3	53.1 ± 8.6

100% Bypass		Circuit-Clamp	Continuous	Counter-pulse	Co-pulse
HR	83.4 ± 14.0		83.0 ± 13.1	80.9 ± 12.6	82.6 ± 10.7
Mean CVP (mmHg)	11.4 ± 6.4		9.8 ± 4.9	10.6 ± 5.7	10.4 ± 6.0
Mean AoP (mmHg)	61.4 ± 12.3		58.4 ± 8.4	59.2 ± 9.6	60.5 ± 10.0
Mean LVP (mmHg)	45.4 ± 13.2		40.1 ± 10.3	39.6 ± 11.2	40.6 ± 10.5
Pump Flow(L/min)	0.0 ± 0.0		4.0 ± 1.2	4.1 ± 1.4	3.8 ± 1.0
Total Flow (L/min)	2.8 ± 1.3		3.8 ± 1.4	4.0 ± 1.3	3.7 ± 1.2
Bypass Rate (%)	0.0 ± 0.0		108.2 ± 10.1	106.4 ± 9.8	105.3 ± 8.8

Bypass rates were adjusted to 50 or 100 % for each mode. Aortic flow in the circuit-clamp mode was decreased to approximately 60 % of the baseline value. There were no significant differences from the data obtained with LVAD

Inferior vena cava occlusion was performed to make the loop. The vertical axis is the left ventricular pressure, and the horizontal axis is the left ventricular volume. The left ventricular EDV was increased in the co-pulse mode (rightward shift), and was decreased in the counter-pulse mode (leftward shift). External work is equivalent to the area enclosed by the pressure volume curve. This is also decreased in the counter-pulse mode, and increased in the co-pulse mode as compared to the continuous mode.

Discussion

With the goal of improving the function of the native heart employing LVAD, and allowing patients a BTR course, we developed a novel driving system, the Native Heart Load Control System (NHLCS), for continuous-flow LVAD. The first concern at the development was the effect of LVAD pulsatility. Many reports have compared clinical outcomes or effects on circulatory dynamics between pulsatile and continuous-flow LVAD [6–27]. The norepinephrine level, which is higher in the non-pulsatile than in the pulsatile LVAD, may affect oxygen metabolic conditions and worsen systemic oxygen uptake in the acute phase [10–13]. The systemic vascular resistance response to norepinephrine decreased markedly with non-pulsatile flow. From the viewpoint of hemodynamic change, pulsatile flow generates more energy, which may be beneficial for vital organ perfusion [14], with the amount depending on the timing of mechanical cardiac beating [15, 16]. Pulsatile flow may be beneficial for the end-organ micro-circulation [17] and for coronary flow [18], but the effect on brain metabolism remains a source of controversy [20–22]. The vascular system is also affected by pulsatility [23]. Structural

change in the aortic wall, caused by atrophy of aortic smooth muscle cells, occurs with non-pulsatile flow [24–27]. In summary, the overall systemic effects of long-term support with continuous LVAD have yet to be determined. We simply do not know which effects, if any, are beneficial or harmful. However, as to clinical outcomes, unfavorable results with pulsatile LVAD have been reported [6]. These may, however, arise from the higher risks of complications with pulsatile LVAD. In our view, the ability of pulsatile LVAD to provide physiological circulation is a benefit that cannot be denied.

Thus, we developed the NHLCS, with which we can drive the continuous-flow LVAD synchronized with the actual cardiac rhythm. Our recent report was the first description of such a pulsatile driving technique [30–36]. Herein, we aimed to confirm the effect of this system on the native heart load from the aspect of MVO₂, which we consider to be the most important factor in evaluating native heart load changes. The pressure–volume area (PVA) is defined as the area framed by the lines of the end-diastolic and systolic pressure volume relationship and the pressure–volume curve of the systolic phase. The rectangular area within the pressure volume loop represents the external work performed, and the triangular area under the E_{max} line (end-systolic slope of the pressure volume relationship as maximum elastance) represents the elastic potential energy stored in the left ventricle. Therefore, PVA is considered to be equivalent to the sum of external work and potential energy. Furthermore, PVA is known to show a strong positive correlation with MVO₂. [37–41] Thus, the MVO₂, the amount of oxygen used by the left ventricle, is closely related to cardiac energy dynamics, and is the most useful factor for evaluating the native heart load. The MVO₂ is the optimal parameter to represent

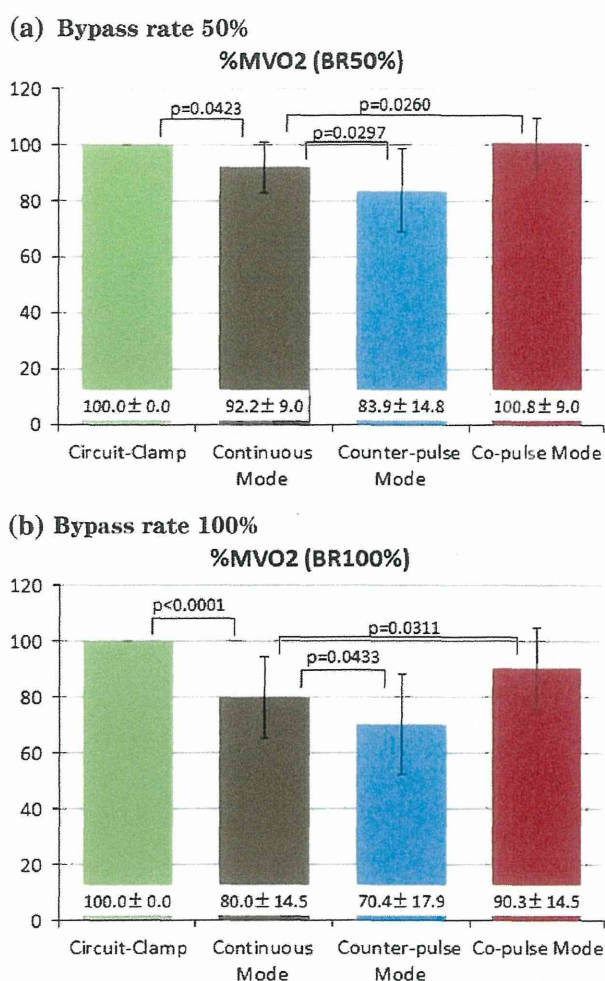


Fig. 3 Amount of myocardial oxygen consumption (circuit-clamp = 100). The amount of MVO2 was decreased by LVAD in acute ischemic heart failure models. MVO2 decreased in the counter-pulse mode and increased in the co-pulse mode relative to the continuous mode ($p < 0.05$) for both the 50 % (Fig. 3a) and the 100 % (Fig. 3b) bypass rates

oxygen utilization and energy use by the myocardium under ischemic conditions. This is why we chose MVO2 as the parameter for assessing the NHLCS effect on the native heart load. In addition, in this study, we aimed to evaluate the effect of NHLCS on acute heart failure models. In these models, the myocardial oxygen demand is inevitably higher than in normal heart models, due to the suppression of myocardial perfusion. High end-diastolic pressure and sympathetic hyperactivity with high catecholamine concentrations may greatly exacerbate these demands. However, in response to the increased oxygen requirements, low oxygen delivery may occur due to insufficient myocardial perfusion, caused by stenosis of the coronary artery itself, high intra-myocardial pressure, low blood pressure and so on. It is quite interesting to evaluate changes in the

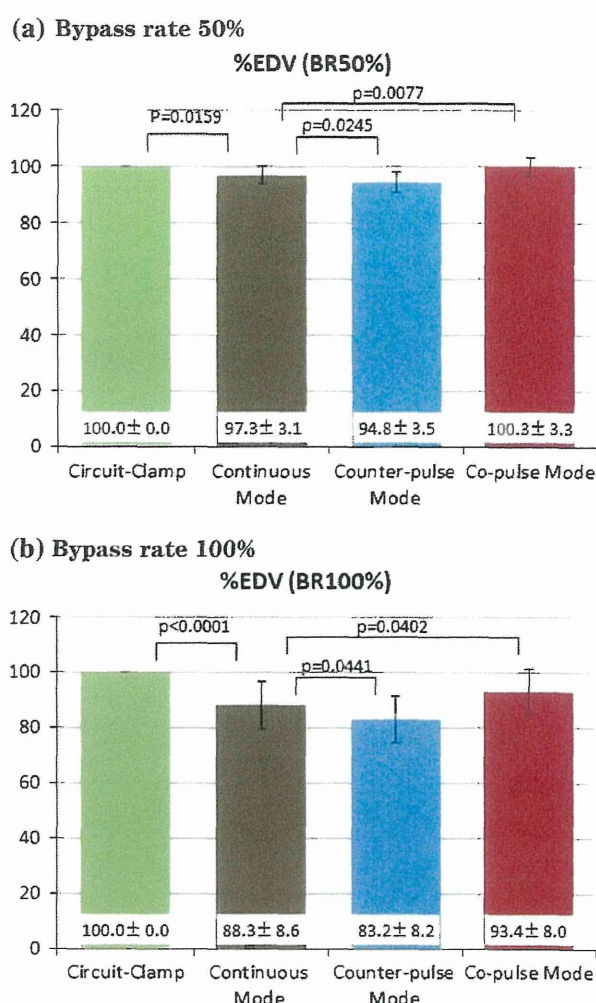
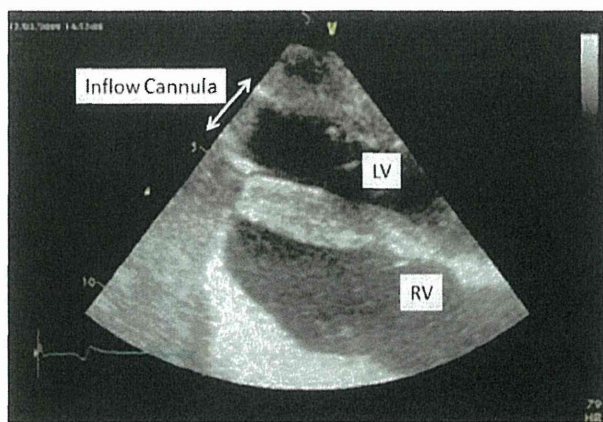


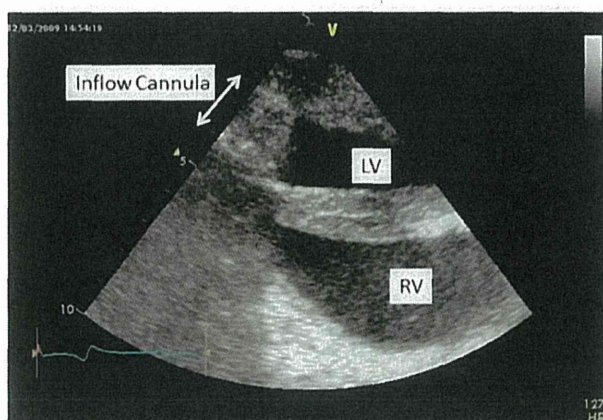
Fig. 4 Left ventricular end-diastolic volume in various modes (circuit-clamp = 100). EDV was decreased by LVAD. EDV decreased in the counter-pulse mode and increased in the co-pulse mode relative to the continuous mode ($p < 0.05$) for both the 50 % (Fig. 4a) and the 100 % (Fig. 4b) BR

myocardial oxygen dynamic state with NHLCS under ischemic conditions.

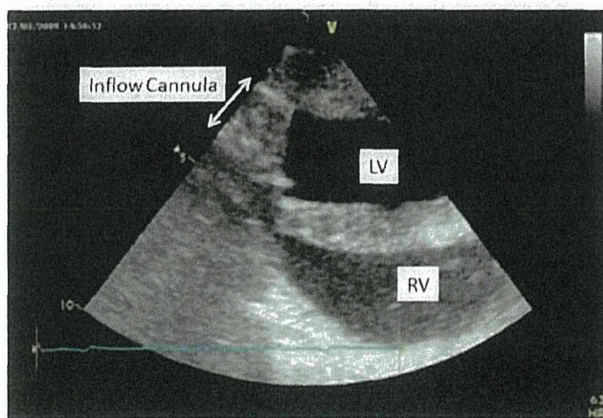
In such a situation, we have demonstrated the possibility of changing the MVO2 intentionally with our NHLCS. First, when comparing the circuit-clamp and continuous modes, MVO2 was decreased with LVAD whether the myocardium was ischemic or not. This result is consistent with the outcomes of other reports [42–46]. Simply put, this observation means that the native heart load is reduced with LVAD because it carries part of the burden on the native heart (external workload). This may partially be explained by the decrease in EDV with LVAD [41]. According to the Frank-Starling law of the heart, the external work applied against afterload relies upon the EDV. This means that cardiac energy metabolism is greatly



(a) Continuous mode

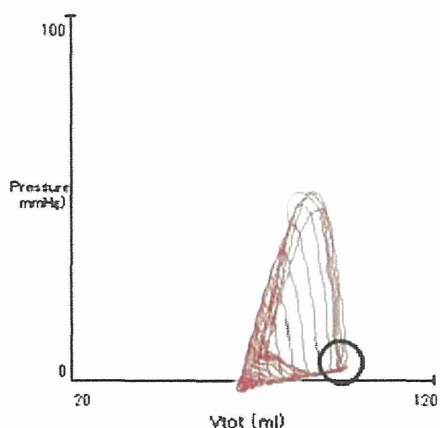


(b) Counter-pulse mode

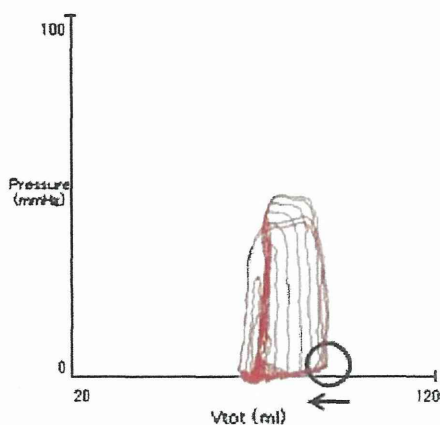


(c) Co-pulse mode

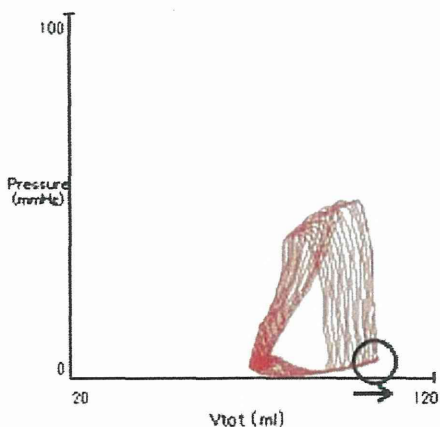
Fig. 5 Echocardiography of the end-diastolic phase (a continuous mode, b counter-pulse mode, c co-pulse mode). The size of the left ventricle was significantly decreased in the counter-pulse mode (b) and increased in the co-pulse mode (c), as compared with that in the continuous mode (a)



(a) Continuous mode



(b) Counter-pulse mode



(c) Co-pulse mode

Fig. 6 Samples of pressure volume loops in the continuous mode (a), counter-pulse mode (b) and co-pulse mode (c). The left ventricular end-diastolic volume (EDV) was increased in the co-pulse mode (*rightward shift*), and was decreased in the counter-pulse mode (*leftward shift*)

influenced by EDV. Theoretically, it is easy to understand that LVAD can decrease the native heart load and MVO₂ via its volume unloading effect.

Changing our frame of reference to the difference in MVO₂ between the two experimental driving modes, the MVO₂ amount was decreased with the counter-pulse mode and increased with the co-pulse mode, as compared with the continuous mode. This trend was apparent regardless of the cardiac state or the BR [31], and the same trend was recognized for the difference in EDV [36]. The EDV was confirmed to be one of the determinants of MVO₂, based on our present results. Considering the equivalence between MVO₂ and the native heart load, the significance of this result is that we may have a chance to produce a desirable load suiting the condition of the native heart by choosing our novel driving mode of continuous-flow LVAD. With the counter-pulse mode, we can reduce the native heart load by unloading the ventricular volume for patients with acute ischemic heart failure in the counter-pulse mode. However, when full LVAD support is needed for a severely failing heart, it may be more favorable to choose the counter-pulse mode with its heart load reduction effect. Furthermore, raising RS in the diastolic phase may induce left ventricular unloading and provide an AoP boost-up effect, which would especially benefit patients with ischemia via its so-called counter-pulse effect mimicking that of intra-aortic balloon pumping. On the other hand, in the co-pulse mode, the load is increased to the level of the circuit-clamp mode, even though the heart has an installed LVAD. We can create more strain on the native heart by loading it with excess volume when we want to train the native heart, or to assess the possibility of weaning from the LVAD in the recovery stage. The strain level is almost the same as if the LVAD is detached. Therefore, if we choose the appropriate mode of NHLCS according to the various clinical situations encountered on the road to recovery, we may have a chance to create the ideal conditions for the native heart by providing the most suitable load.

These results may be mistakenly understood to mean that the LVAD has the potential only to provide a small amount of oxygen. It may well be assumed that it would be natural for the native heart to use more oxygen than in the condition without LVAD, after attaching the LVAD to the acute ischemic heart, and establishing the system to provide more CoF and oxygen to myocardium. However, this would simply be due to the decrease in myocardial oxygen demand, secondary to the reduced native heart load and the sufficient CoF. Especially with the counter-pulse mode, the oxygen demand may be decreased with the EDV and native heart load reductions. However, conversely, with the co-pulse mode, the demand may be increased.

Goldstein implicated various indices of energy metabolism, external work, PVA, the tension-time index, the

integral of systolic force, and intra-cardiac pressure, as major determinants of MVO₂, in a report on the effects of a low BR driving the LVAD [43]. On the other hand, there were no correlations between MVO₂ and parameters associated with the oxygen delivery potential (AoP in diastole, the amount of CoF, and myocardial oxygen delivery [CoF × O₂ content of arterial blood]). They also noted that the severely failing myocardium was quite sensitive to even the slight relief provided by LVAD, not because the oxygen supply was augmented, but because oxygen requirements were diminished. When we install the LVAD in an ischemic heart, MVO₂ depends on the native heart load, not on the oxygen delivery condition. It may be smaller than that without LVAD, because of the substantial reduction in the native heart load with diminished oxygen demand, rather than because of an insufficient oxygen supply. These results are in good agreement with our observations.

This study has limitations. First of all, our results are based on an acute ischemic heart failure model, such that it is unclear whether the same results would apply to the chronically failing heart in clinical situations. However, the change in MVO₂ depends on the ventricular hemodynamic state (EDV, etc.), as detailed above. Therefore, we believe the same trend would be seen in the chronically failing heart. We have already begun to evaluate the effects of NHLCS on the native heart, by creating chronic heart failure models. We aim to ascertain the chronic effects of NHLCS, not only on the hemodynamic state and energy metabolism, but also on tissues and genetic expressions including the reverse remodeling effect. The second limitation involves the mechanical factor. Herein, we defined the spans of the systolic and diastolic phases as 35 and 65 % of the RR interval based on our experience with goats. However, there may well be marked alterations in these parameters among individuals or according to the state of the native heart. In addition, the timing of synchronization is problematic, because the continuous-flow LVAD is characterized by the RS changing gradually, i.e., within minutes rather than seconds. If we incorporate a signal to change the RS, it will still take some time to obtain the ideal RS. Therefore, we must confirm whether the timings of the maximum or minimum RS are attuned to the cardiac cycle. For this study, we employed data with which the LVAD rotation was in synchrony with the heartbeat, in terms of span and timing. We are now endeavoring to adjust the system for NHLCS, which has the capacity to change the span and timing of synchronization according to the native heartbeat. The third limitation may be the site of the outflow graft. Usually, we place the outflow graft of the LVAD at the ascending aorta. In this study, however, we placed it in the descending aorta, because of the shortness of the ascending aorta in goats. These animals have a bovine carotid artery which diverges

from the ascending aorta near the base of the heart. Furthermore, all of the carotid and subclavian arteries bifurcate from this bovine artery. We will need to examine outflow grafts placed at the ascending aorta in the future. Although these differences may have impacted the cardiac after-load, many reports suggest equivalence between these outflow graft sites [51, 52].

Herein, we demonstrated the possibility of changing the native heart load employing NHLCS, based on changes in MVO₂. This means that a desirable native heart load can be produced by choosing our novel driving mode of continuous-flow LVAD. We may thus be able to create the appropriate conditions for BTR. We can reduce the native heart load for patients with severe heart failure in the counter-pulse mode. On the other hand, we can create more strain on the native heart in the co-pulse mode when assessing the possibility of weaning from the LVAD in the recovery stage. Further studies are underway, including analyses of cardiac energy metabolism and myocardial perfusion using chronic heart failure models.

Conclusion

Based on our experimental results in goats with acute ischemic heart failure, LVAD can change MVO₂. The MVO₂ was reduced with the counter-pulse mode and increased with the co-pulse mode, relative to the continuous support mode, which we usually apply in clinical practice. This means that we can change the native heart load by controlling the LVAD rotation in synchrony with the cardiac rhythm. The changeable native heart load made by NHLCS may enhance the chance of BTR, especially for patients with ischemic heart diseases.

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Development of a novel drive mode to prevent aortic insufficiency during continuous-flow LVAD support by synchronizing rotational speed with heartbeat

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Abstract Aortic insufficiency (AI) is a serious complication for patients on long-term support with left ventricular assist devices (LVAD). Postoperative aortic valve opening is an important predictor of AI. A system is presently available that can promote native aortic flow by reducing rotational speed (RS) for defined intervals. However, this system can cause a reduction in pump flow and lead to insufficient support. We therefore developed a novel “delayed copulse mode” to prevent AI by providing both minimal support for early systole and maximal support shortly after aortic valve opening by changing the RS in synchronization with heartbeat. To evaluate whether our drive mode could open the aortic valve while maintaining a high total flow (sum of pump flow and native aortic flow), we installed a centrifugal LVAD (EVAHEART®; Sun Medical) in seven goats each with normal hearts and acute LV dysfunction created by micro-embolization of the coronary artery. We intermittently switched the drive mode from continuous (constant RS) with 100 % bypass to

delayed copulse mode with 90 % bypass. Total flow did not significantly change between the two modes. The aortic valve opened when the delayed copulse mode was activated. The delayed copulse mode allowed the aortic valve to open while maintaining a high total flow. This novel drive mode may considerably benefit patients with severe heart failure on long-term LVAD support by preventing AI.

Keywords Delayed copulse mode · Aortic valve opening · Aortic insufficiency · Continuous-flow LVAD · Synchronization with heartbeat

Introduction

Left ventricular assist devices (LVAD) have become widely applied as a therapeutic option for patients with end-stage heart failure, and long-term LVAD support has become more important not only as a bridge to transplantation, but also as a destination therapy [1]. However, native aortic insufficiency (AI) can develop during long-term LVAD support [2–4]. Severe AI can lead to reduced forward cardiac output and increased LV preload due to recycling regurgitant blood flow from the LVAD outflow graft into the left ventricular inflow cannula, which in turn decreases the effectiveness of LVAD support and results in end-organ malperfusion. Survival rates are significantly worse for patients with, than without, AI [5]. Closure of the aortic valve after LVAD implantation is a significant predictor of AI [3–6]. Persistent closure of the aortic valve after LVAD implantation might promote reduced valve pliability and commissural fusion, consequently resulting in the occurrence or progression of AI. The aortic valve must be able to open on demand during LVAD support to prevent AI. The intermittent low-speed (ILS) mode

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promotes native aortic flow (AoF) by reducing rotational speed (RS) for a defined interval. However, this system is inappropriate for patients with severe heart failure because it can result in support flow that is insufficient to meet the requirements of patients. A methodology to resolve this issue is not available. Therefore, we developed a “delayed copulse mode” that can prevent AI by synchronization with the cardiac cycle in continuous-flow LVAD. The aim of this mode is to provide both minimal support during early systole to open the aortic valve and maximal support shortly after the valve has opened to maintain high pump flow (PF). Here, we compared the effects of this mode on aortic valve opening and PF with the ILS mode in animal models of normal and acute ischemic heart failure.

Materials and methods

Experimental preparation

We studied seven goats (52.6 ± 4.1 kg) with normal hearts and seven (52.3 ± 4.9 kg) with acute LV dysfunction created by coronary microsphere embolization of the left anterior descending coronary artery (LAD). All animals were sedated with an intramuscular injection of ketamine (10 mg/kg). General anesthesia was induced and maintained by isoflurane inhalation (1–3 vol/100 mL in oxygen). The animals were fixed in the right lateral recumbent position, intubated and mechanically ventilated. The fifth costal bone was resected via a left thoracotomy and the heart was approached through the left thoracic space. A centrifugal LVAD (EVAHEART; Sun Medical Technology Research Corporation, Nagano, Japan) was installed [7, 8] after heparinization (300 U/kg) by inserting the inflow cannula into the left ventricular apex and suturing the outflow graft to the descending aorta. Blood flow in the ascending aorta and LVAD was measured using electromagnetic (EMF-1000: diameter, 16–18 mm; Nihon Kohden, Tokyo, Japan) and ultrasonic (TS420: 16 mm; Transonic Systems) flow meters, respectively. Pressure lines for monitoring aortic (AoP) and central venous pressure (CVP) were established from the left internal thoracic artery and the left internal thoracic veins, and a pressure line for left ventricular pressure (LVP) monitoring was inserted into the left ventricle from the anterior wall. Pacing leads for ventricular electrocardiography were sutured onto the anterior wall of the right ventricle. The vital data described above were recorded using Labchart 5 software (ADInstruments, Bella Vista NSW, Australia). We calculated the instantaneous left ventricular-aortic pressure gradient (LV-Ao PG) by subtracting AoP from LVP. We evaluated aortic valve opening by echocardiography, and measured the aortic valve area (AVA) by echocardiographic planimetry.

The animals used in this study were maintained in accordance with the guidelines of the Committee on Animal Studies at the National Cerebral and Cardiovascular Center. This study was approved by the National Cerebral and Cardiovascular Center Animal Investigation Committee. Institutional guidelines for the care and use of laboratory animals were observed.

Making left ventricular dysfunction models

We created animal models of acute ischemic heart failure by micro-embolizing the LAD as described [9–11]. A multipurpose, 4 Fr Judkins catheter (Create Medic Co. Ltd., Yokohama, Japan) was introduced through a long sheath (4 Fr \times 17 cm) into the left carotid artery towards the LAD under fluoroscopic guidance. We then injected $3.14 \pm 0.29 \times 10^4$ microspheres (diameter, 75 μ m; 600/kg) into the LAD. We planned to reduce and then maintain cardiac output at about 60 % of the native heart function determined before creating the model of acute ischemic heart failure. After 30 min of observation, we collected data to assure stable optimal cardiac function. We stabilized the AoP and CVP throughout the experiment to ensure that heart afterload or preload remained constant, and that heart rate also remained constant by adjusting infusion volumes and changing the depth of anesthesia. Neither vasodilators nor catecholamines were used. Ventricular arrhythmias were prevented during the experiment using 2 % lidocaine (1 mg/kg/h).

Study protocol and drive mode

We previously described a novel pump controller in which the RS changes in synchrony with the cardiac cycle [12–18]. The controller can detect R waves from the ventricular ECG and momentarily change the RS to target speed. The RS was controlled using the delayed copulse mode in each of the early systolic, ejection period and diastolic phases of the cardiac cycle (Fig. 1). During early systole, LVP must exceed AoP to allow the aortic valve to open, and some left ventricular end diastolic volume (LVEDV) is needed to increase LVP. Therefore, we adjusted the RS of diastole to avoid inducing reverse flow. We set the RS of early systole at 700 rpm (the minimum RS for this LVAD) to minimize early systole support. Thereafter, we momentarily increased the RS of the ejection period and adjusted the RS to achieve the appropriate bypass rate to maintain high support flow. We defined early systole, ejection period and diastole as 11, 22 and 67 % of the RR interval, respectively and compared the following drive modes.

The first was the intermittent delayed copulse (IDCO) mode that was intermittently activated for every 10 of 80 cardiac beats with a triggered R wave. This means that for

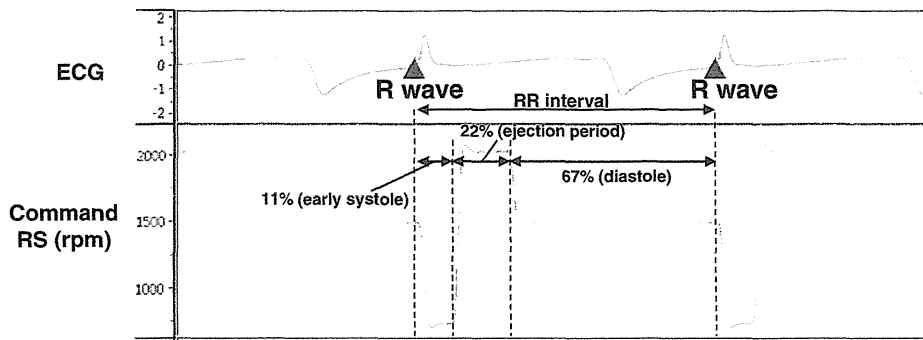


Fig. 1 Command rotational speed in delayed copulse mode. ECG electrocardiogram, RS rotational speed. Pumps were driven at early systolic RS of 700 rpm from R-wave input for 11 % of RR interval. Ejection period RS increased to target speed and was maintained for

22 % of RR interval. Diastolic RS instantly reduced to achieve diastolic PF of ~0 L/min, maintained RS for remaining 67 % of RR interval, and finally returned to initial early systolic RS of 700 rpm

70 beats we ran continuous mode (constant RS) and then switched to delayed copulse mode for the next 10 beats. The bypass rate (BR) was set at around 100 and 90 % in the continuous and delayed copulse modes, respectively. The second was the ILS mode using a Jarvik 2000 (Jarvik Heart Inc., New York, NY, USA) [19] as follows. We decreased the RS from 100 % bypass to low speed (1,200 rpm) for 10 of 80 heartbeats. We calculated BR by dividing PF by total flow (TF: sum of PF and AoF) and then assessed the effects of the delayed copulse and low-speed modes upon aortic valve opening, PF, AoF, and hemodynamic parameters. All data were compared with those generated using a circuit clamp (no pump support) as a control condition (Table 2; Figs. 3, 5).

Statistics

All numerical data are shown as averages ± standard deviation (SD). Groups were compared using a repeated-measures analysis of variance followed by Tukey’s multiple comparison test. All analyses were two-sided, and a *p* value <0.05 was considered statistically significant. All data were analyzed using PASW Statistics ver. 20 (IBM SPSS).

Results

Table 1 shows the average RS in the continuous and delayed copulse modes. The RS required to achieve 100 % bypass in continuous mode was around 1,800 and 1,650 rpm in the animal models with a normal heart and in those with acute ischemic heart failure, respectively. The RS of the ejection period needed to achieve 90 % bypass in delayed copulse mode was ~2,100 and 2,000 rpm in the animals with a normal heart and in the models, respectively. The RS of diastolic phase required to avoid reverse

Table 1 Rotational speed

Mode (rpm)	Continuous mode	Delayed copulse mode
Normal heart		
Early systolic RS	1,800 ± 82	700 ± 0
RS of ejection period	1,800 ± 82	2,100 ± 129
Diastolic RS	1,800 ± 82	1,550 ± 87
Heart failure		
Early systolic RS	1,729 ± 76	700 ± 0
RS of ejection period	1,729 ± 76	2,050 ± 217
Diastolic RS	1,729 ± 76	1,471 ± 95

Data are shown as averages ± standard deviation
RS rotational speed

flow in delayed copulse mode was 1,700 and 1,450 rpm in the animal models with a normal heart and with acute ischemic heart failure, respectively. Figure 2 shows typical waveforms of pressure and flow data when continuous mode with 100 % bypass was switched to either the delayed copulse or the low-speed mode in the models of acute ischemic heart failure. The AoF increased and the PF slightly decreased in delayed copulse mode. The AoF increased and the PF significantly decreased along with the RS reduction in the low-speed mode. Pulse pressure and the instantaneous maximum LV-Ao PG were increased in both the delayed copulse and low-speed modes when activated.

Table 2 shows numerical hemodynamic data. Changes in heart rate and mean AoP did not significantly differ between continuous and either delayed copulse or low-speed modes. Pulse pressure significantly increased in both delayed copulse and low-speed modes, compared with the continuous mode (*p* < 0.05). Left ventricular end systolic pressure (LVESP) and mean LVP tended to be higher in both delayed copulse and low-speed modes, than in the

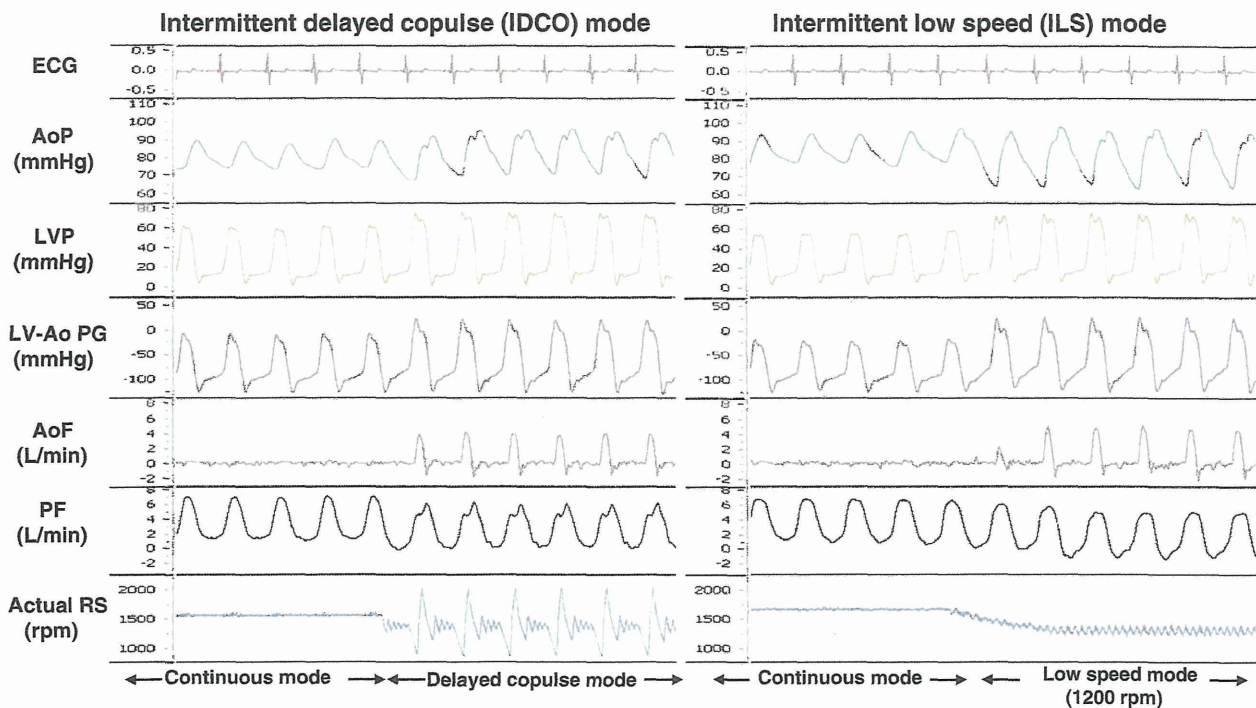


Fig. 2 Sample waveforms of pressure and flow data. *AoF* ascending aortic flow, *AoP* aortic pressure, *ECG* electrocardiogram, *IDCO* intermittent delayed copulse, *ILS* intermittent low speed, *LV-Ao* left ventricular-aortic pressure gradient, *LVP* left ventricular pressure, *PF* pump flow, *RS* rotational speed. Waveforms typical at the portion switched from continuous mode with 100 % bypass to either delayed

copulse or low-speed (1,200 rpm) mode in animal models of acute ischemic heart failure. *AoF* increased and *PF* slightly decreased in delayed copulse mode. *AoF* increased and *PF* significantly decreased along with reduction of *RS* in low-speed mode. Pulse pressure and maximal *LV-Ao* PG were instantaneously increased in both delayed copulse and low-speed modes when activated

continuous mode. Instantaneous maximum *LV-Ao* PG was obviously increased in both delayed copulse and low-speed modes ($p < 0.05$). Left ventricular end diastolic pressure (*LVEDP*) significantly differed between the delayed copulse and low-speed modes in the models of acute heart failure. Delayed copulse mode activation improved pulsatility and *LVEDP* did not significantly change.

Figure 3a, b show the 80-beat average of *TF* in circuit-clamp, continuous, *IDCO*, and *ILS* modes. The *TF* in *IDCO* mode tended to be larger than that in the *ILS* mode, but the difference did not reach significance. Figures 3c, d show a 10-beat average of *TF* when the delayed copulse and the low-speed modes are activated, and in circuit-clamp, continuous mode. When the drive mode was switched from continuous to low-speed mode, *PF* significantly decreased, but the native heart could not keep up with it, and thus *TF* decreased ($p < 0.01$). The decreased ratio of *TF* was higher in the models ($37.8 \pm 8.8\%$) than in animals with a normal heart ($31.4 \pm 10.3\%$). On the other hand, *TF* in delayed copulse mode did not significantly change in animals with a normal heart and in the models of acute ischemic heart disease.

Figure 4 shows echocardiography in the short axis view of the aortic valve in models of acute ischemic heart

failure. The aortic valve did not open in the continuous mode with 100 % bypass. Valve opening was better in the delayed copulse, than in the low-speed mode.

Figure 5 shows changes in *AVA* after the mode switch. The *AVA* significantly increased after switching the drive mode in both the delayed copulse and low-speed modes in the models ($p < 0.01$). In animal models of acute heart failure, the *AVA* in the delayed copulse mode was larger than in the low-speed mode ($p < 0.01$). These results indicated that the aortic valve opened in delayed copulse mode while high *TF* was maintained. However, *TF* decreased in the low-speed mode after the aortic valve opened.

Discussion

The REMATCH trial demonstrated that long-term mechanical cardiac support is clinically effective as destination therapy [20], and thus LVADs have become increasingly popular as long-term therapy for patients with end-stage heart failure. However, prolonged LVAD support remarkably alters cardiac and vascular physiology and function. The development of AI during long-term LVAD

Table 2 Pressure data

	Mode	Circuit-clamp	Continuous	Delayed copulse	low-speed (1,200 rpm)
	Normal heart				
	Heart rate (bpm)	79.9 ± 19.1	80.2 ± 20.5	75.3 ± 23.0	80.9 ± 19.7
	Mean AoP (mmHg)	62.9 ± 10.1	65.9 ± 7.2	59.6 ± 13.0	58.6 ± 9.8
	Pulse pressure (mmHg)	35.4 ± 4.6	19.6 ± 7.2	28.3 ± 6.0*	36.3 ± 5.8*
	Mean LVP (mmHg)	38.4 ± 10.2	24.1 ± 9.4	29.7 ± 9.0	36.8 ± 10.8
	LVESP (mmHg)	89.2 ± 12.3	68.7 ± 9.0	82.8 ± 14.8	86.0 ± 13.6*
	LVEDP (mmHg)	10.1 ± 5.4	7.07 ± 5.7	8.3 ± 4.4	12.0 ± 7.2
	Max LV-Ao PG (mmHg)	32.2 ± 4.6	-0.9 ± 6.4	28.8 ± 5.2*	27.8 ± 7.6*
	Bypass rate (%) ^a	0.0 ± 0.0	100.5 ± 1.9	90.0 ± 4.8*	36.0 ± 8.0* [†]
	Heart failure				
	Heart rate (bpm)	76.1 ± 7.9	74.1 ± 9.0	71.9 ± 9.7	74.3 ± 8.6
	Mean AoP (mmHg)	59.7 ± 12.9	62.9 ± 10.1	59.5 ± 10.9	58.4 ± 12.2
	Pulse pressure (mmHg)	28.9 ± 4.8	17.2 ± 8.3	29.3 ± 8.0*	29.6 ± 4.7*
	Mean LVP (mmHg)	37.5 ± 9.5	22.6 ± 8.7	31.1 ± 5.1	31.2 ± 7.8
	LVESP (mmHg)	81.4 ± 15.6	58.6 ± 18.7	72.5 ± 11.4	72.0 ± 10.6
	LVEDP (mmHg)	24.6 ± 3.1	18.5 ± 2.6	19.9 ± 1.9	25.3 ± 3.4* [†]
	Maximal LV-Ao PG (mmHg)	22.8 ± 4.5	-10.9 ± 13.9	20.4 ± 4.1*	13.2 ± 2.7* [†]
	Bypass rate (%) ^a	0.0 ± 0.0	107.5 ± 9.8	88.5 ± 4.4*	79.5 ± 8.0* [†]

All data are shown as averages ± standard deviation
AoF Ascending aortic flow, *AoP* aortic pressure, *AVA* aortic valve area, *LVEDP* left ventricular end diastolic pressure, *LVESP* left ventricular end systolic pressure, *LVP* left ventricular pressure, *PF* pump flow, *PG* pressure gradient, *TF* total flow (sum of PF and AoF)
 * $p < 0.05$ and [†] $p < 0.05$ compared with continuous and delayed copulse mode, respectively
^a Bypass rate, calculated by dividing PF by sum of PF and AoF

is regarded as the most important complication, because survival is significantly worse for patients with, than without, AI due to insufficient LVAD support and end-organ mal-perfusion [5].

Less frequent aortic valve opening significantly correlates with more severe AI [3–6], and Hatano et al. [4] reported that the incidence of AI is higher in patients with a continuous-flow than with a pulsatile-flow LVAD. Because almost all pulsatile devices function in asynchrony with the native cardiac cycle, the loading condition of the LV changes with each heartbeat. Therefore, the aortic valve is more likely to open in patients with pulsatile- than with continuous-flow LVADs. Among preoperative clinical parameters, a lower LV ejection fraction is an independent risk factor for the development of AI [4, 5]. Poor LV contractile function might contribute to inefficient aortic valve opening. Toda et al. [5] reported that preoperative functional mitral regurgitation (MR) is related to AI progression. This is because severe MR could lead to the aortic valve opening less frequently due to regurgitant blood flowing into the left atrium during LVAD support.

The loss of pulsatility caused by continuous-flow LVADs seems to closely correlate with AI development. A healthy aortic valve has a significantly redundant coaptation surface. The coaptation area of the normal aortic valve is directly related to the diameter of the aortic root, which is sensitive to root pressure [21]. We speculated that the same hemodynamic alterations induced by continuous-flow LVAD, loss of pulsatility and persistent elevation of aortic

root pressure, cause aortic root dilation. Pressure in the ascending aorta is persistently higher than LVP in such patients and native aortic valves consequently do not open.

Mudd et al. [6] found evidence that a commissural fusion in eight of nine patients with continuous-flow LVAD correlated with decreased valve opening and an increasing prevalence of AI. Letsou et al. [22] identified some degree of commissural fusion in 51.5 % of patients on LVAD support, and a histopathological examination of areas of fusion revealed loose fibrous tissue between commissures. Pak et al. [3] identified significantly larger aortic root circumferences in patients with, than without AI.

From the above, we speculate that the main causes of AI are persistent aortic valve closure and elevated aortic root pressure. These can lead to commissural fusion, reduced valve pliability, and aortic root dilation, and consequently result in the occurrence or development of AI during long-term LVAD support. To open the aortic valve and improve pulsatility, pump flow should be reduced to promote the native AoF. However, this can reduce support flow and result in insufficient support to meet physiological requirements. Our delayed copulse mode can resolve these issues.

Our results showed that the delayed copulse mode could open the aortic valve and improve pulsatility while maintaining high bypass flow. The delayed copulse mode is characterized by minimal support of the early systolic phase and maximal support soon after the aortic valve has

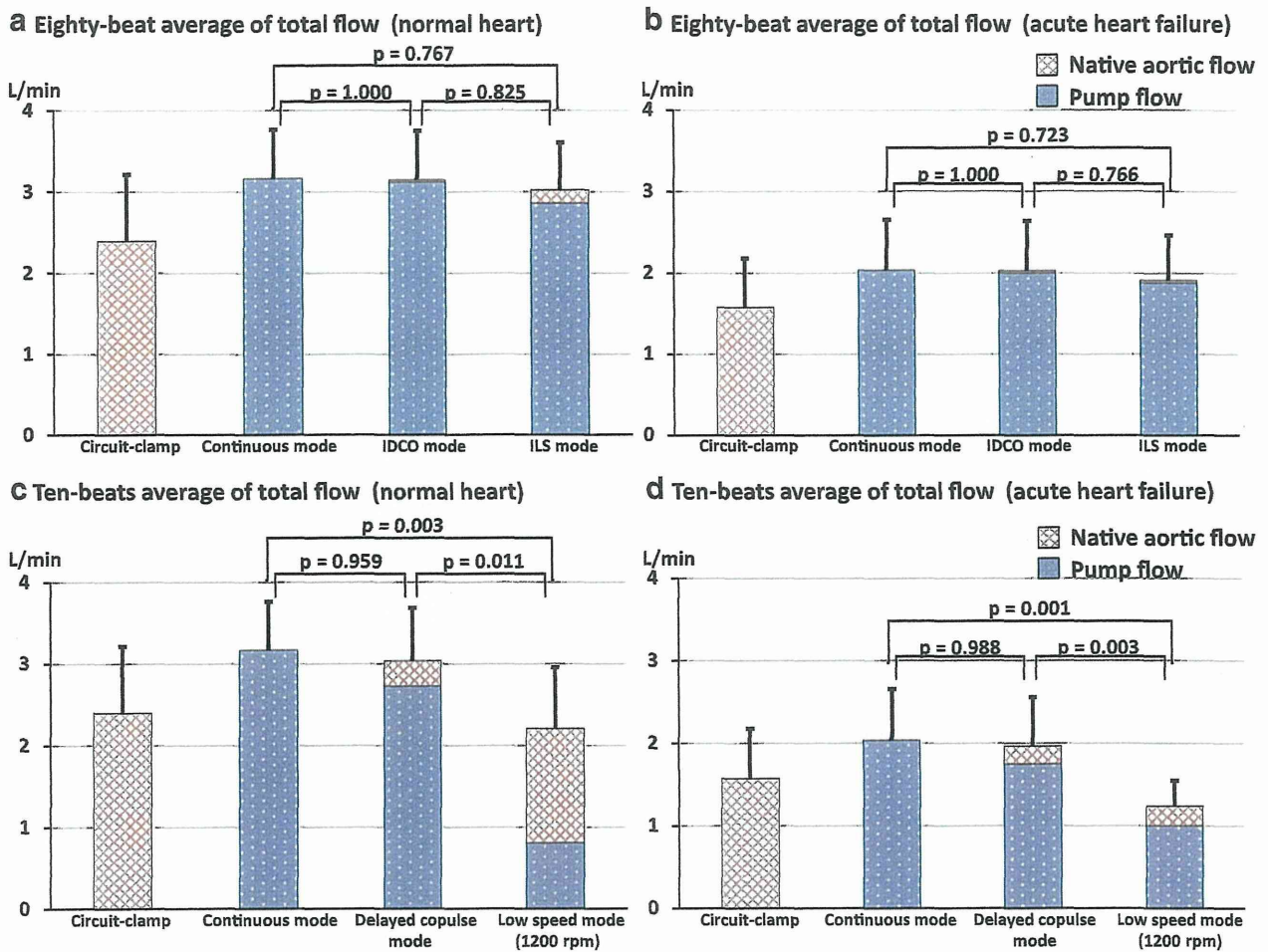


Fig. 3 a, b 80-beat average of total flow (TF) data in circuit-clamp (control condition), continuous, intermittent delayed copulse (IDCO) and intermittent low-speed (ILS) modes. TF, sum of pump (blue) and native aortic (red) flow. Continuous, IDCO and ILS modes did not significantly differ in normal animals (a) and in models of acute heart failure (b). Total flow in IDCO mode tended to be larger than in the ILS mode, but the two modes did not significantly differ between these two modes in both groups of animals. Figure 3c, d 10-beat average of

total flow (TF) data in circuit-clamp (control condition), continuous, delayed copulse and low-speed (1,200 rpm) modes. TF sum of pump (blue) and native aortic (red) flow. During mode switch, TF did not significantly change between continuous and the delayed copulse modes in normal animals (c) and in models of acute heart failure (d). After mode switch, TF significantly decreased between continuous and low-speed modes in both groups of animals. Delayed copulse and low-speed modes also significantly differed in both groups of animals

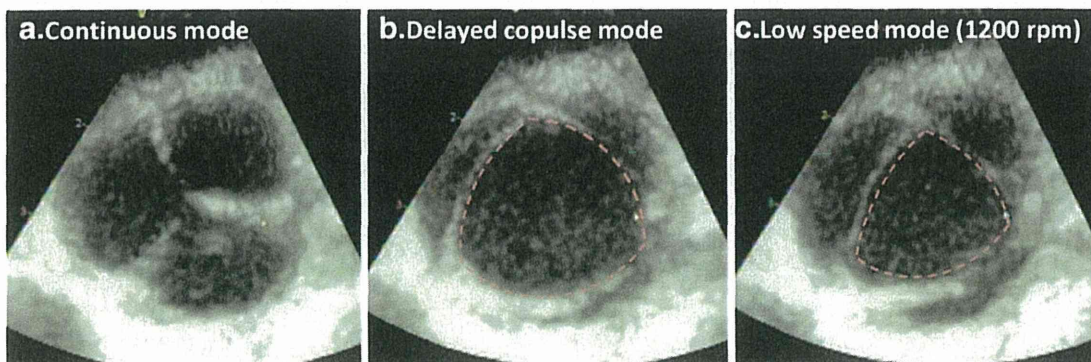


Fig. 4 Echocardiography in short axis view of aortic valve in animal models of acute ischemic heart failure (a, b and c, continuous, delayed and low-speed (1,200 rpm) modes, respectively), Dotted line

maximal aortic valve area in each mode. Aortic valve did not open in continuous mode (a), but opened more efficiently in delayed copulse, than in low-speed mode (b, c)

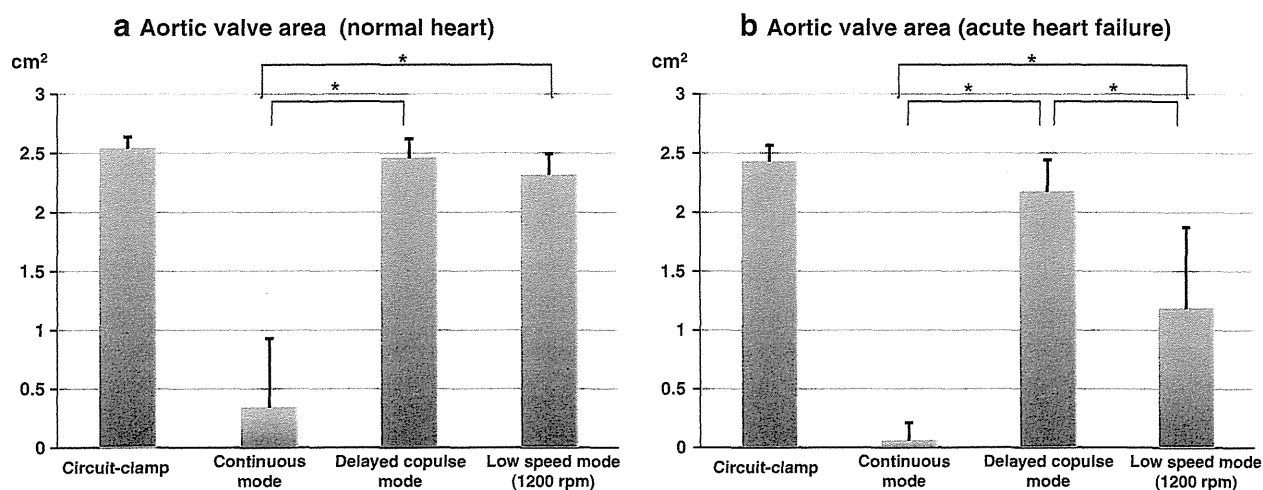


Fig. 5 Aortic valve area (AVA) in circuit-clamp (control condition), continuous, delayed copulse and low-speed (1,200 rpm) modes. Asterisk significant difference ($p < 0.01$). After switching, AVA

significantly increased in both delayed copulse and low-speed modes (a, b) and these two modes significantly differed (b) in animal models of acute heart failure ($p < 0.01$)

opened. Therefore, this unique drive mode can open the aortic valve while maintaining high bypass flow. The delayed copulse mode could open the aortic valve without reducing the TF not only in the normal heart but also in the animal models of acute heart failure. These findings indicate that the delayed copulse mode will be effective for patients with low cardiac output. Furthermore, because LVEDP did not significantly change between continuous mode and delayed copulse modes, the latter might be able to maintain adequate LV unloading.

We demonstrated that the 80-beat average of TF in the ILS mode tended to be smaller than that in the continuous mode, and that the two modes did not significantly differ (Fig. 3a, b). However, TF significantly decreased when the low-speed mode was activated (Fig. 3c, d). This tendency was evident in animal models of acute heart failure with LV dysfunction compared with animals with a normal heart. We speculate that preprogrammed intermittent reduction of pump speed can maintain TF for long periods, but this also has a risk of not providing sufficient support to meet physiological requirements at slow pump speeds. From this perspective, we believe that the delayed copulse mode carried an extremely small risk of insufficient support that could result in transient ischemic attacks.

The EVAHEART is an implantable centrifugal blood pump with a flat pressure-flow curve that can provide a significantly high PF rate. This feature can provide higher flow during systole and lower flow during diastole, thus providing pulsatile high-flow, which can solve the current clinical problems with the continuous-flow LVAD [7, 8]. With respect to AI, higher flow during systole might interfere with aortic valve opening. In contrast, high pulsatility might prevent AI development because of a lower

pressure effect during diastole. Therefore, we speculate that the EVAHEART confers both an advantage and a disadvantage against AI. The concept of the delayed copulse mode is to overcome the disadvantage by opening the aortic valve and to enhance the advantage by improving its pulsatility.

The delayed copulse mode has some possible negative aspects. First, it might elevate hemolysis levels due to high shear stress caused by a momentary increase in the RS. The effects on blood should be evaluated using hemolysis tests in vitro and by long-term studies of animal models of chronic heart failure. The long-term effects on device durability should be similarly evaluated. The delayed copulse mode might increase regurgitant blood flow during early diastole in patients with extant mild AI, because the pressure effect caused by an increase of the RS during the ejection period can be slightly delayed. However, even if patients have mild AI before LVAD implantation, the likelihood that LV preload increases in the delayed copulse mode is hardly conceivable. This is because we adjusted the RS of diastole to avoid inducing reverse flow in delayed copulse mode, and thus regurgitant blood flow can be reduced during the mid- and late-diastole as compared with continuous mode.

The present study has several limitations. Our results are based on animals with a normal heart and an animal model of acute ischemic heart failure. Thus, to determine whether or not the same results would apply to chronic heart failure in the clinical setting is difficult. We have not yet examined the effectiveness of the long-term application of the delayed copulse mode, or its effects on pathological changes of the aortic valve. We have started to evaluate the effects of delayed copulse mode on the native heart in

animal models of chronic heart failure. We aim to assess the effects of the delayed copulse mode on hemodynamics, pathological changes in the aortic valve and device durability in a larger study of animal models of chronic heart failure. We defined early systole, the ejection period, and diastole as 11, 22, and 67 % of the RR interval, respectively. However, these parameters might widely differ among individuals or according to the status of the native heart. If we prolong early systole, the aortic valve will be easier to open, but maintaining high support flow will become more difficult. Therefore, the appropriate interval of each phase needs to be determined according to the status of the native heart in the clinical setting. In addition, a method of actual adjustment of the RS of the ejection period and diastolic phase in the clinical setting needs to be established. Monitoring PF during pump support is difficult with the current system and BR needs to be estimated in the clinical setting by echocardiography. The delayed copulse mode was intermittently activated for every 10 out of 80 cardiac beats with a triggered R wave. However, it is not possible to determine whether this intermittent interval is optimal for preventing AI during long-term LVAD support from experiments on animals with acute conditions. Delayed copulse mode should perhaps be activated throughout sleep. However, the optimal method for preventing AI remains unclear.

Conclusions

Our delayed copulse mode allowed aortic valve opening while maintaining high pump flow in goats with normal and acute ischemic hearts. This novel drive mode might confer considerable benefits upon patients with chronic heart failure on long-term LVAD support by preventing AI. Further investigation is currently underway in models of chronic heart failure.

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Conflict of interest The authors have no conflicts of interest to disclose.

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Development and evaluation of endurance test system for ventricular assist devices

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Abstract We developed a novel endurance test system that can arbitrarily set various circulatory conditions and has durability and stability for long-term continuous evaluation of ventricular assist devices (VADs), and we evaluated its fundamental performance and prolonged durability and stability. The circulation circuit of the present endurance test system consisted of a pulsatile pump with a small closed chamber (SCC), a closed chamber, a reservoir and an electromagnetic proportional valve. Two duckbill valves were mounted in the inlet and outlet of the pulsatile pump. The features of the circulation circuit are as follows: (1) the components of the circulation circuit consist of optimized industrial devices, giving durability; (2) the pulsatile pump can change the heart rate and stroke length (SL), as well as its compliance using the SCC. Therefore, the endurance test system can quantitatively reproduce various circulatory conditions. The range of reproducible circulatory conditions in the endurance test circuit was examined in terms of fundamental performance. Additionally, continuous operation for 6 months was performed in order to evaluate the durability and stability. The circulation circuit was able to set up a wide range of pressure and total flow conditions using the SCC and

adjusting the pulsatile pump SL. The long-term continuous operation test demonstrated that stable, continuous operation for 6 months was possible without leakage or industrial device failure. The newly developed endurance test system demonstrated a wide range of reproducible circulatory conditions, durability and stability, and is a promising approach for evaluating the basic characteristics of VADs.

Keywords Endurance test · Circulation circuit · Ventricular assist devices (VADs) · Pulse duplicator · Field: artificial heart (basic)

Introduction

Ventricular assist devices (VADs) are widely used in patients with serious heart failure [1–4]. VADs require validity, safety and reliability; therefore, it is necessary to conduct animal experiments and pump performance tests, hemolysis tests and endurance tests, and the performance of VADs must be fully evaluated in order to extract and analyze potential problems in preclinical studies [5–9]. In particular, implantable VADs have become mainstream in recent years; therefore, durability and reliability are required for VADs that will be used in the body for long periods of time. Therefore, it is necessary to evaluate VADs over long periods of time under physiologically relevant pulsatile load conditions using test equipment that can reproduce the circulatory conditions of the living human body [10].

Test equipment using a pulse duplicator with a flexible diaphragm or sac similar to a ventricle has been proposed in order to generate pulsatile flow similar to circulatory conditions [11–13]. There was a report that the diaphragm

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